



CSI 60: User Interface Design

Human Information Processing (KLM, GOMS, Fitts' law) 03/03/10

Berkeley
UNIVERSITY OF CALIFORNIA




<http://www.youtube.com/watch?v=WHxQU4RhyLk>



Most heavily used features directly mapped (volume, play/pause)
Circular movements mapped to linear operations

Individual Programming Assignment 4 (due Mar 3)



Assignment: Low Fidelity Prototype

Due Mar 15

Identify project mission statement

Create low-fidelity prototype that supports 3 tasks

1 easy, 1 moderate, 1 difficult task

Create a video prototype showing (cameras next class)

How it supports the 3 tasks

Context in which is will be used (back story)

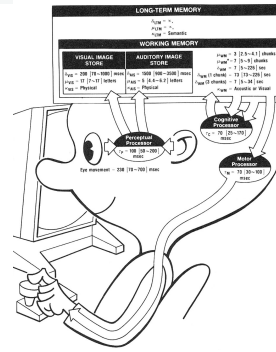
Must include narration

Test the prototype with target users

No one from this class

Not your friends

Review: Human Info Processor



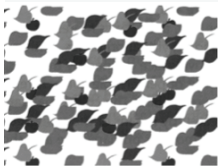
5 Parts

- Perceptual
- Cognitive
- Motor (will discuss today)
- Working memory
- Long-term memory

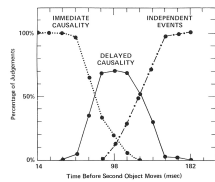
Unified model

- Probably inaccurate
- Predicts perf. well
- Very influential

Review: Pop-Out and Causality



Michotte demonstration 1 What do you see? Most observers report that "the red ball hit the blue ball." The film had never "shown" the red ball hit it. Thus, the red ball is perceived to "cause" the blue ball to move, even though the balls are nothing more than color disks on your screen that move according to a program.



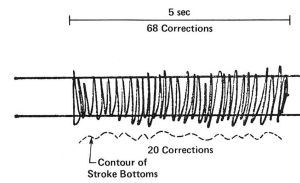
Motor Processor

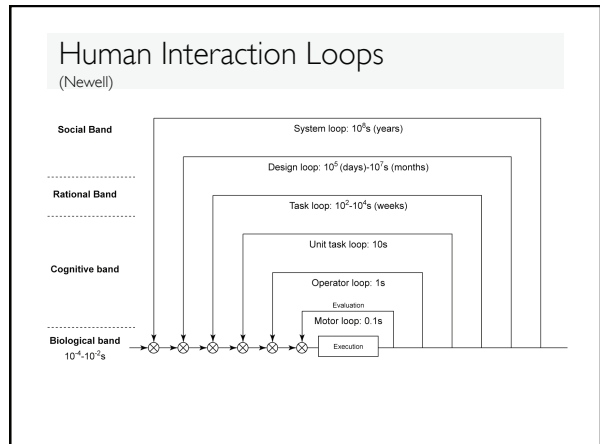
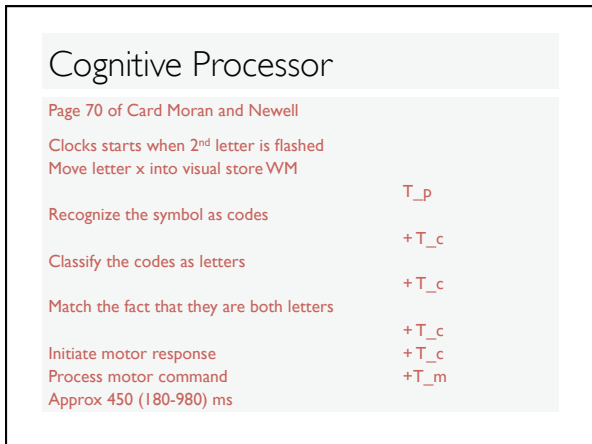
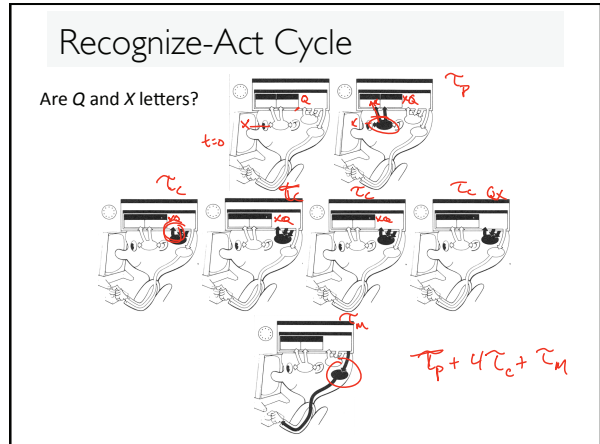
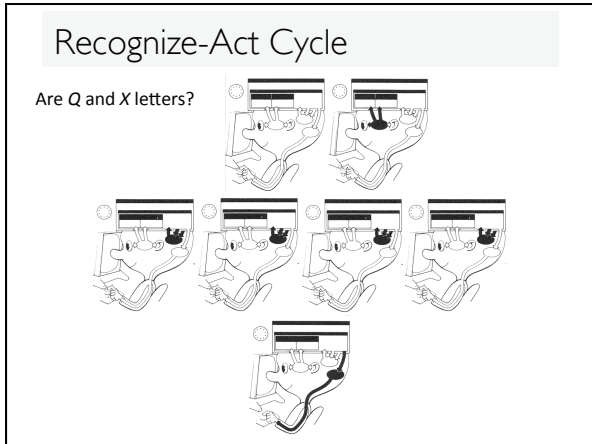
Receive input from the cognitive processor

Execute motor programs

Pianist: up to 16 finger movements per second

Point of no-return for muscle action





Principles of Operation

Interface should respect limits of human performance

Preattentive features pop-out
Events within cycle time fuse together
Causality

Recognize-Act Cycle of the cognitive processor

On each cycle contents in WM initiate cognitive actions
Cognitive actions modify the contents of WM

Discrimination Principle

Retrieval is determined by candidates that exist in memory relative to retrieval cues

Interference by strongly activated chunks

Two strong cues in working memory
Link to different chunks in long term memory

Topics

Memory
Decision Making and Learning
Fitts' Law
GOMS and KLM

Memory

Simple Experiment

Volunteer

Start saying colors you see in list of words

When slide comes up

As fast as you can

Say "done" when finished

Everyone else time it...

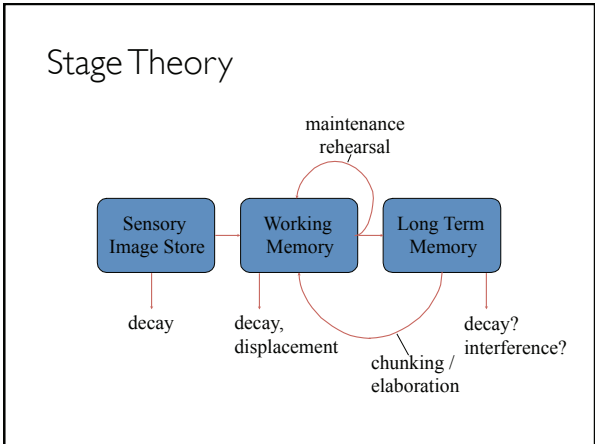
Schedule
Paper
Page
Back
Change
Home

Simple Experiment

Do it again

Say "done" when finished

Blue
Red
Black
White
Green
Yellow



Stage Theory

Working memory is small

Temporary storage

decay
displacement

Maintenance rehearsal

Rote repetition

Not enough to learn information well

LTM and Elaboration

Recodes information

Organize (chunking)

Relate new material to already learned material

Link to existing knowledge, categories

Attach meaning

Make a story

LTM Forgetting

Causes for not remembering an item?

- 1) Never stored: encoding failure
- 2) Gone from storage: storage failure
- 3) Can't get out of storage: retrieval failure

Interference model of forgetting

One item reduces ability to retrieve another

Proactive interference (3)

Earlier learning reduces ability to retrieve later info.

Retroactive interference (3 & 2)

Later learning reduces the ability to retrieve earlier info.

Recognition over Recall

Recall

Info reproduced from memory

Recognition

Presentation of info helps retrieve info (helps remember it was seen before)

Easier because of cues to retrieval

We want to design UIs that rely on recognition!

Recall



Recognition

Grouchy
Sneezy
Smiley
Sleepy
Pop
Grumpy
Cheerful
Dopey
Bashful
Wheezy
Doc
Lazy
Happy
Nifty

Recognition

Grouchy
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Wheezy
Doc
Lazy
Happy
Nifty

Facilitating Retrieval: Cues

Any stimulus that improves retrieval

Example: giving hints

Other examples in software?

icons, labels, menu names, etc.

Anything related to

Item or situation where it was learned

Decision Making and Learning

Hick's Law

Cost of taking a decision: $T = a + b \log_2(n + 1)$

The left graph shows a linear relationship between Reaction Time (msec) on the y-axis (0 to 600) and $\log_2(n + 1)$ on the x-axis (0 to 3). The right graph shows Reaction Time (msec) on the y-axis (0 to 800) versus Bits Per Stimulus Presentation on the x-axis (0 to 4). Data points are categorized by stimulus information: Number of Alternatives (circles), Stimulus Probabilities (squares), and Sequential Dependencies (triangles). The regression equation is $RT = 212 + 153 H$ with a correlation coefficient $r = .985$.

Power Law of Practice

Task time on the nth trial follows a power law

$$T_n = T_1 n^{-a} + c$$

where $a = .4$, $c =$ limiting constant

Power Law of Practice

Task time on the nth trial follows a power law

$$T_n = T_1 n^{-a} + c$$

You get faster the more times you do it!

The graph shows a scatter plot of Time to solution, sec (y-axis, 0 to 1400) versus Number of problems (k) (x-axis, 0 to 100). The data points show a clear downward trend, indicating that task time decreases as the number of problems increases, following a power law.

Power Law of Practice

Task time on the nth trial follows a power law

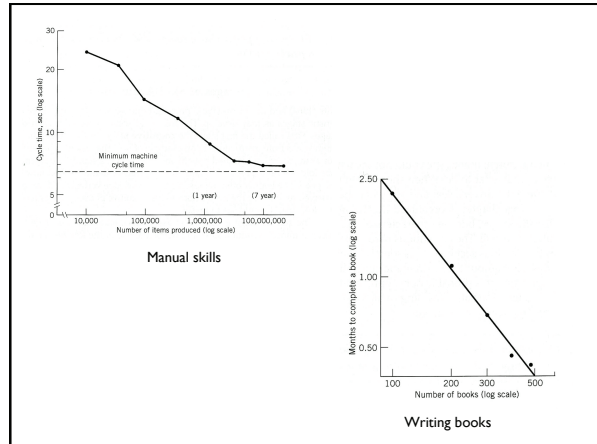
$$T_n = T_1 n^{-a} + c$$

where $a = .4$, $c =$ limiting constant

You get faster the more times you do it!

Applies to skilled behavior (sensory & motor)

Does not apply to
Knowledge acquisition
Improving quality



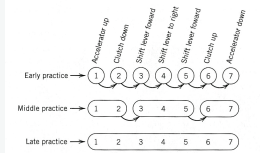
Stages of skill acquisition

Example: Using a manual transmission

Cognitive
Verbal representation of knowledge

Associative
Proceduralization
Form of chunking

Autonomous
More and more automated
Faster and faster
No cognitive involvement
Difficult to describe what to do

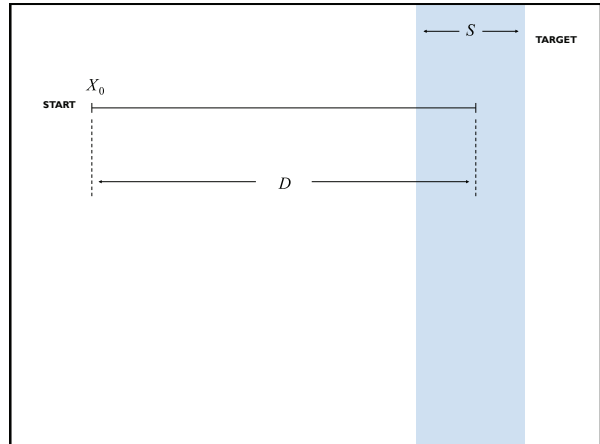


Fitts' Law

Motor Processor

Receive input from the cognitive processor
Execute motor programs

Pianist: up to 16 finger movements per second
Point of no-return for muscle action



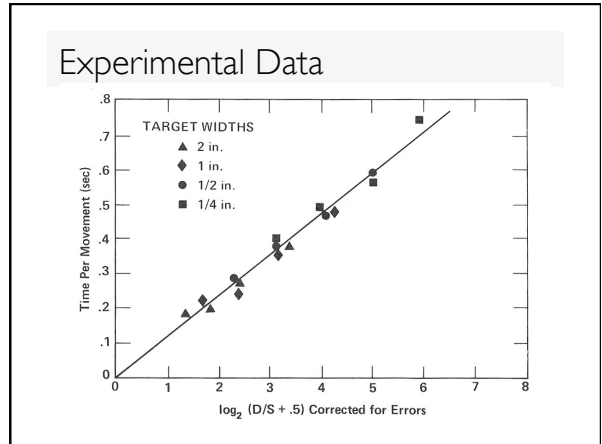
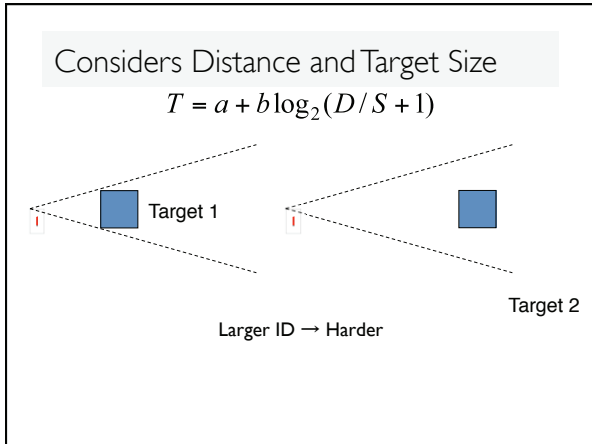
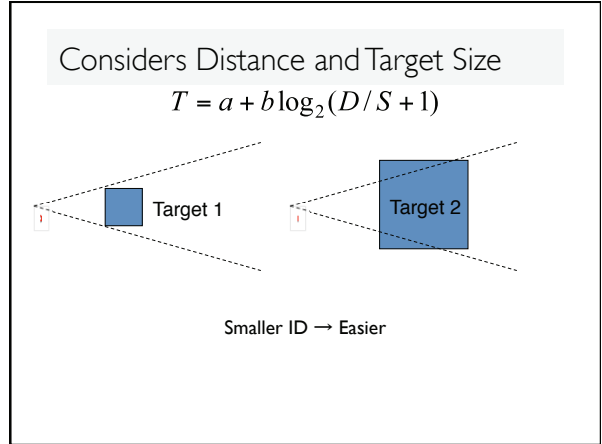
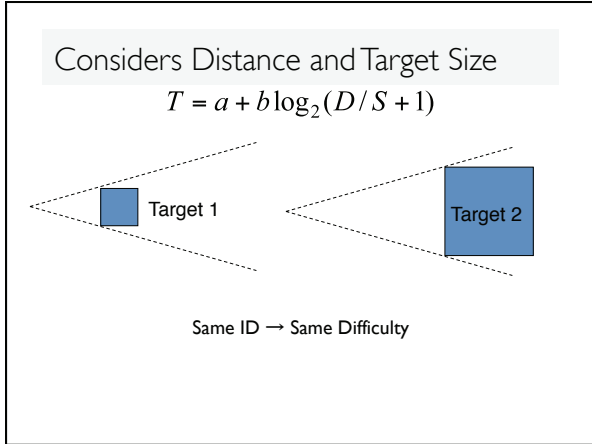
Hand movement based on series of microcorrections
 X_i = remaining distance after i th move
 Relative movement accuracy remains constant $\rightarrow \frac{X_i}{X_{i-1}} = \epsilon$

Fitts' Law

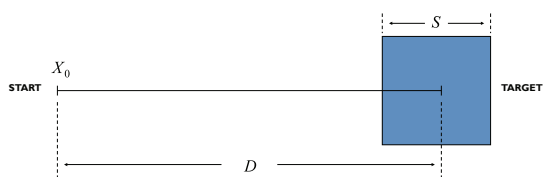
$$T = a + b \log_2(D/S + 1)$$

a, b = constants (empirically derived)
 D = distance
 S = size
 ID is Index of Difficulty = $\log_2(D/S + 1)$

Models well-rehearsed selection task
 T increases as the **distance** to the target increases
 T decreases as the **size** of the target increases

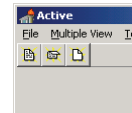
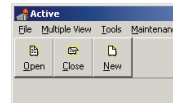


Extend Fitts' Law to 2D Targets?



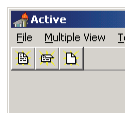
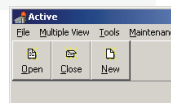
Toolbar Example

Microsoft Toolbars offer the user the option of displaying a label below each tool. Name at least one reason why labeled tools can be accessed faster. (Assume, for this, that the user knows the tool.)



Toolbar Example

1. The label becomes part of the target. The target is therefore bigger. Bigger targets, all else being equal, can always be accessed faster, by Fitts' Law
2. When labels are not used, the tool icons crowd together



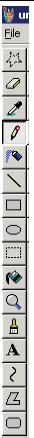
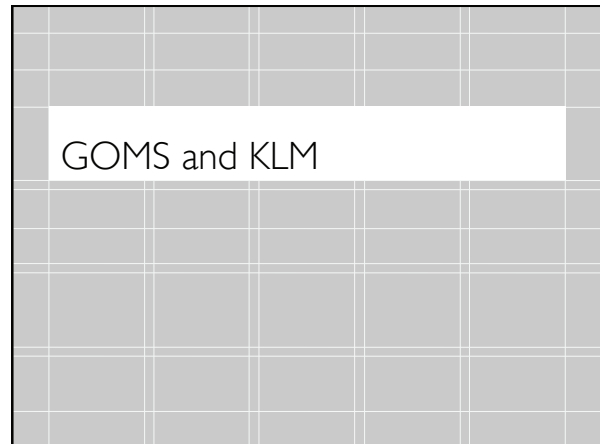
Tool Matrix Example

You have a palette of tools in a graphics application that consists of a matrix of 16×16 -pixel icons laid out as a 2×8 array that lies along the left-hand edge of the screen. Without moving the array from the left-hand side of the screen or changing the size of the icons, what steps can you take to decrease the time necessary to access the average tool?



Tool Matrix Example

1. Change the array to 1x16, so all the tools lie along the edge of the screen.
2. Ensure that the user can click on the very first row of pixels along the edge of the screen to select a tool. There should be no buffer zone.

GOMS (Card et al.)

Describe the user behavior in term of

Goals
Edit manuscript, locate line

Operators
Elementary perceptual, motor or cognitive acts

Methods
Procedure for using operators to accomplish goals

Selection rules
Used if several methods are available for a given goal

Family of methods
KLM, CMN-GOMS, NGOMSL, CPM-GOMS

Quick Example

Goal (the big picture)
Go from hotel to the airport

Operators (or subgoals)?
Walk, take bus, take taxi, rent car, take train

Methods (or specific actions)
locate bus stop; wait for bus; get on the bus;...

Selection rules (choosing among methods)?
Example: Walking is cheaper, but tiring and slow
Example: Taking a bus is complicated abroad

GOMS Output

Execution time

Add up times from operators/methods
Assumes **experts** (mastered the tasks)

Error free behavior

Very good rank ordering
Absolute accuracy ~10-20%

Using GOMS Analysis

Check that frequent goals can be achieved quickly

Making operator hierarchy is often the value

Functionality coverage & consistency

Does UI contain needed functions?

Consistency: are similar tasks performed similarly?

Operator sequence

In what order are individual operations done?

How to do GOMS Analysis

Generate task description

Pick high-level user **Goal**

Write **Operators** for reaching Goal - may invoke subgoals

Write **Methods** for each Operator

This is recursive

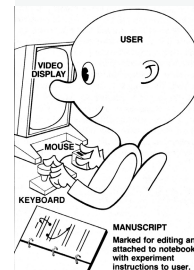
Stops when **methods** are reached

Evaluate description of task

Apply results to UI

Iterate!

Detailed Task Description



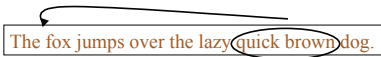
```

GOAL: EDIT-MANUSCRIPT
. GOAL: EDIT-UNIT-TASK      repeat until no more unit tasks
. . GOAL: ACQUIRE-UNIT-TASK
. . . GET-NEXT-PAGE        if at end of manuscript page
. . . GET-NEXT-TASK
. . GOAL: EXECUTE-UNIT-TASK
. . . GOAL: LOCATE-LINE
. . . . [select: USE-QS-METHOD
. . . . . USE-LF-METHOD]
. . . GOAL: MODIFY-TEXT
. . . . [select: USE-S-COMMAND
. . . . . USE-M-COMMAND]
. . . . . VERIFY-EDIT .
  
```

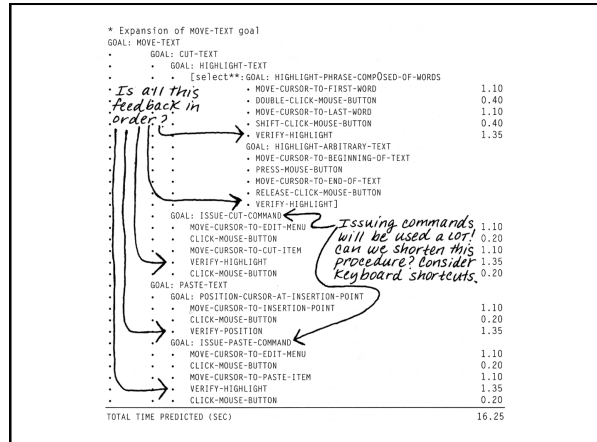
MANUSCRIPT:
Marked for editing and
attached to notebook
with experiment
instructions to user.

GOMS Example II

Using a text editor edit the following text as shown



- Goals and sub-goals?
- Operators?
- Methods?
- Selection rules?



Keystroke Level Model (KLM)

Describe the task using the following operators:

K: pressing a key or a pressing (or releasing) a button
 $t_k = 0.08 - 1.2s$ (0.2 good rule of thumb)

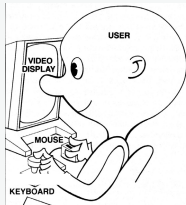
P: pointing
 $t_p = 1.1s$ (without button press)

H: Homing (switching device)
 $t_H = 0.4s$

D(n,l): Drawing segmented lines
 $t_D = 0.9*n + .16*l$

M: Mentally prepare
 $t_M = 1.35s$

R(t): system response time
 $t_R = t$



KLM Heuristic Rules (Raskin's)

0: Insert M
 In front of all K
 In front of all P's selecting a command (not in front of P's ending command)

1: Remove M between fully anticipated operators
 PMK → PK

2: if a string of MKs belong to cognitive unit delete all M but first
 4564.23: MKMKMKMKMKMKMK → MKKKKKKK

3: if K is a redundant terminator then delete M in front of it
 ↓↓: MKMK → MKK

4a: if K terminates a constant length string (command name) delete the M in front of it
 cd ↓: MKMK → MKK

4b: if K terminates a variable length string (parameter) keep the M in front of it
 cd class ↓: MKKKMKKKMK → MKKKMKKKMK

Using KLM

Encode using all physical operator (K, P, H, D(n,l), R(t))

Apply Raskin's KLM rules [0-4]

Transform R followed by an M

If $t \leq t_M : R(t) \rightarrow R(0)$

If $t_M < t : R(t) \rightarrow R(t - t_M)$

Compute the total time by simply adding all time